

Robust Covariance Matrix Estimators for Sparse Data Using Regularization and RMT

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Contents

Part A (Done)

Esa

Regularized M -estimators of covariance:

- M -estimation and geodesic (g -)convexity
- Regularization via g -convex penalties
- Application: regularized discriminant analysis

Part B (Here we are)

Frederic

Regularized M -estimators and RMT

- Robust estimation and RMT
- Regularized M -estimators
- Application(s): DoA estimation, target detection

Outline

I. Introduction

- Motivations
- Results

II. Estimation, background and applications

- Modeling the background
- Estimating the covariance matrix
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I. Introduction

- Motivations
- Results

II. Estimation, background and applications

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V. Conclusions and perspectives

Motivations ...

Signal Processing applications

- Application reality: only observations \Rightarrow Unknown parameters
- Several SP applications require the covariance matrix estimation, e.g. sources localization, STAP, Polarimetric SAR classification, radar detection, MIMO, discriminant analysis, dimension reduction, PCA...
- The ultimate purpose is to characterize the system performance, not only the estimation performance \Rightarrow ROC curves, PD vs SNR, PFA, MSE ...

Motivations ...

Robustness: what happens when models turn to be not Gaussian anymore?

- Gaussian model \Rightarrow Sample Covariance Matrix
- Outliers and other parasites
- Mismodelling
- Missing data

High dimensional problems

- Massive data
- Data size can be important...
- ... greater than the number of observations
- Link with robustness.

Some insights

* Robust Estimation Theory

- More flexible and adjustable models \rightsquigarrow *CES distributions*
 - Robust family of estimators \rightsquigarrow *M-estimators*
 - Regularized estimators (cf. Part A)
- *M-estimators* statistical properties (complex case)
 - Statistical properties of *M-estimators* functionals (e.g. MUSIC statistic for DoA estimation, ANMF detectors...)
 - Regularized Tyler Estimator (RTE) derivation and asymptotics

Some insights

* (Robust) Random Matrix Theory

In many applications, the dimension of the observation m is large (HSI...)

⇒ The required number N of observations for estimation purposes needs to be larger: $N \gg m$ BUT this is not the case in practice! Even $N < m$ is possible

↪ New asymptotic regime: $N \rightarrow \infty, m \rightarrow \infty$ and $\frac{m}{N} \rightarrow c \in [0, 1]$

- Extension of “standards” for M -estimators for particular case and for general CES distribution.
- Asymptotic distribution of the eigenvalues
- Asymptotics for the RTE
- Application to DoA estimation: robust G-MUSIC

Connections between Robust Estimation Theory and RMT

Key references of this talk

Robust Estimation Theory

- E. Ollila, D. E. Tyler, V. Koivunen, and H. V. Poor, “Complex elliptically symmetric distributions: Survey, new results and applications,” *Signal Processing, IEEE Transactions on*, vol. 60, pp. 5597-5625, nov. 2012.
- [F. Pascal](#), Y. Chitour and Y. Quek, “Generalized Robust Shrinkage Estimator and Its Application to STAP Detection Problem,” *Signal Processing, IEEE Transactions on*, vol. 62, pp. 5640-5651, nov. 2014.
- A. Kammoun, R. Couillet, [F. Pascal](#) and M-S. Alouini, “Convergence and fluctuations of Regularized Tyler estimators,” *Signal Processing, IEEE Transactions on*, vol. 64, pp. 1048-1060, feb. 2016.

Key references of this talk

(Robust) Random Matrix Theory

- R. Couillet, F. Pascal and J. W. Silverstein, “The Random Matrix Regime of Maronna’s M -estimator with elliptically distributed samples”, *Journal of Multivariate Analysis*, vol. 139, pp. 56-78, 2015.
- (R. Couillet, F. Pascal and J. W. Silverstein, “Robust Estimates of Covariance Matrices in the Large Dimensional Regime,” *Information Theory, IEEE Transactions on*, vol. 60, pp. 7269-7278, nov 2014.)
- R. Couillet, A. Kammoun, and F. Pascal, “Second order statistics of robust estimators of scatter. Application to GLRT detection for elliptical signals,” *Journal of Multivariate Analysis*, vol.143, pp. 249-274 2016.
- A. Kammoun, R. Couillet, F. Pascal, and M.-S. Alouini, “Optimal Design of the Adaptive Normalized Matched Filter Detector,” *submitted*, 2016. arXiv:1501.06027

I. Introduction

II. Estimation, background and applications

- Modeling the background
- Estimating the covariance matrix
- M -estimators asymptotics
- Applications: ANMF and MUSIC

III. Random Matrix Theory

IV. Regularized M -estimators and link to RMT

V. Conclusions and perspectives

Modeling the background

Complex elliptically symmetric (CES) distributions

Let \mathbf{z} be a complex circular random vector of length m . \mathbf{z} follows a CES ($CE(\boldsymbol{\mu}, \boldsymbol{\Lambda}, g_{\mathbf{z}})$) if its PDF can be written

$$g_{\mathbf{z}}(\mathbf{z}) = |\boldsymbol{\Lambda}|^{-1} h_z((\mathbf{z} - \boldsymbol{\mu})^H \boldsymbol{\Lambda}^{-1} (\mathbf{z} - \boldsymbol{\mu})), \quad (1)$$

where $h_z : [0, \infty) \rightarrow [0, \infty)$ is the density generator and is such as (1) defines a PDF.

- $\boldsymbol{\mu}$ is the statistical mean
- $\boldsymbol{\Lambda}$ the scatter matrix

In general (finite second-order moment), $\mathbf{M} = \alpha \boldsymbol{\Lambda}$ where

- $\alpha = -2\varphi'(0)$,
- φ , the **characteristic generator** is defined through the characteristic function $c_{\mathbf{x}}$ of \mathbf{x} by $c_{\mathbf{x}}(\mathbf{t}) = \exp(it^H \boldsymbol{\mu}) \varphi(\mathbf{t}^H \boldsymbol{\Lambda} \mathbf{t})$

Characterizing property

- Unit complex m -sphere:

$$\mathbb{C}S^m \triangleq \{\mathbf{z} \in \mathbb{C}^m \mid \|\mathbf{z}\| = 1\}$$

- \mathbf{u} (or $\mathbf{u}^{(m)}$) = r. v. with uniform distribution on $\mathbb{C}S^m$,

$$\mathbf{u} \sim \mathcal{U}(\mathbb{C}S^m)$$

Theorem (Stochastic representation theorem)

$\mathbf{z} \sim CE(\boldsymbol{\mu}, \boldsymbol{\Lambda}, h_{\mathbf{z}})$ if and only if it admits the stochastic representation

$$\mathbf{z} =_d \boldsymbol{\mu} + \mathcal{R}\mathbf{A}\mathbf{u}^{(k)}$$

where r. va. $\mathcal{R} \geq 0$, called the **modular variate**, is independent of $\mathbf{u}^{(k)}$ and $\boldsymbol{\Lambda} = \mathbf{A}\mathbf{A}^H$ is a factorization of $\boldsymbol{\Lambda}$, where $\mathbf{A} \in \mathbb{C}^{m \times k}$ with $k = \text{rank}(\boldsymbol{\Lambda})$.

Characterizing property

- 1 **One-to-one relation** with c.d.f $F_{\mathcal{R}}(\cdot)$ of \mathcal{R} and characteristic generator $\varphi(\cdot)$
- 2 **Ambiguity**: both $(\mathcal{R}, \mathbf{A})$ and $(c^{-1}\mathcal{R}, c\mathbf{A}), c > 0$ are valid stochastic representations of $\mathbf{z} \Rightarrow$ constraint for identifiability issues
- 3 **Distribution of quadratic form**: if $\text{rank}(\mathbf{\Lambda}) = m$, then

$$Q(\mathbf{z}) \triangleq (\mathbf{z} - \boldsymbol{\mu})^H \mathbf{\Lambda}^{-1} (\mathbf{z} - \boldsymbol{\mu}) =_d \mathcal{Q}$$

where $\mathcal{Q} \triangleq \mathcal{R}^2$ is called the **2nd-order modular variate**.

Estimating the covariance matrix

M-estimators

PDF not specified

⇒ *MLE can not be derived*

⇒ *M-estimators are used instead*

Let $(\mathbf{z}_1, \dots, \mathbf{z}_N)$ be a N -sample $\sim CE(\mathbf{0}, \mathbf{\Lambda}, g_{\mathbf{z}})$ of length m .

The complex M -estimator of $\mathbf{\Lambda}$ is defined as the solution of

$$\mathbf{V}_N = \frac{1}{N} \sum_{n=1}^N u(\mathbf{z}_n^H \mathbf{V}_N^{-1} \mathbf{z}_n^H) \mathbf{z}_n \mathbf{z}_n^H, \quad (2)$$

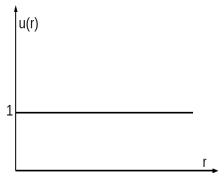
Maronna (1976), Kent and Tyler (1991)

- Existence
- Uniqueness
- Convergence of the recursive algorithm...

Examples of M -estimators

SCM:

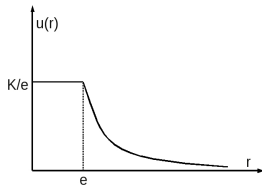
$$u(r) = 1$$



Huber's estimator

(M -estimator):

$$u(r) = \begin{cases} K/e & \text{if } r \leq e \\ K/r & \text{if } r > e \end{cases}$$

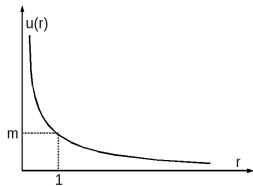


Tyler Estimator

(Tyler, 1987;

Pascal, 2008):

$$u(r) = \frac{m}{r}$$



Remarks:

- Huber = mix between SCM and Tyler
- FP and SCM are “not” M -estimators
- Tyler estimator is the most robust.

Tyler Estimator:

$$\mathbf{V}_N = \frac{m}{N} \sum_{n=1}^N \frac{\mathbf{z}_n \mathbf{z}_n^H}{\mathbf{z}_n^H \mathbf{V}_N^{-1} \mathbf{z}_n}$$

Context

M-estimators

Let us set

$$\mathbf{V} = E \left[u(\mathbf{z}'\mathbf{V}^{-1}\mathbf{z}) \mathbf{z}\mathbf{z}' \right], \quad (3)$$

where $\mathbf{z} \sim CE(\mathbf{0}, \mathbf{\Lambda}, g_{\mathbf{z}})$.

- (3) admits a unique solution \mathbf{V} and $\mathbf{V} = \sigma\mathbf{\Lambda} = \sigma/\alpha\mathbf{M}$ where σ is given by Tyler(1982),
- \mathbf{V}_N is a consistent estimate of \mathbf{V} .

Asymptotic distribution of complex M -estimators

Theorem 1 (Asymptotic distribution of \mathbf{V}_N)

$$\sqrt{N} \operatorname{vec}(\mathbf{V}_N - \mathbf{V}) \xrightarrow{d} \mathbb{CN}(\mathbf{0}, \boldsymbol{\Sigma}, \boldsymbol{\Omega}), \quad (4)$$

where \mathbb{CN} is the complex Gaussian distribution, $\boldsymbol{\Sigma}$ the CM and $\boldsymbol{\Omega}$ the pseudo CM:

$$\begin{aligned} \boldsymbol{\Sigma} &= \sigma_1(\mathbf{V}^T \otimes \mathbf{V}) + \sigma_2 \operatorname{vec}(\mathbf{V}) \operatorname{vec}(\mathbf{V})^H, \\ \boldsymbol{\Omega} &= \sigma_1(\mathbf{V}^T \otimes \mathbf{V}) \mathbf{K} + \sigma_2 \operatorname{vec}(\mathbf{V}) \operatorname{vec}(\mathbf{V})^T, \end{aligned}$$

where \mathbf{K} is the commutation matrix.

Remark: The SCM is defined as $\hat{\mathbf{S}}_N = \frac{1}{N} \sum_{n=1}^N \mathbf{z}_n \mathbf{z}_n^H$ where \mathbf{z}_n are complex independent circular zero-mean Gaussian with CM \mathbf{V} . Then,

$$\sqrt{N} \operatorname{vec}(\hat{\mathbf{S}}_N - \mathbf{V}) \xrightarrow{d} \mathbb{CN}(\mathbf{0}, \boldsymbol{\Sigma}_W, \boldsymbol{\Omega}_W)$$

$$\boldsymbol{\Sigma}_W = (\mathbf{V}^T \otimes \mathbf{V}) \text{ and } \boldsymbol{\Omega}_W = (\mathbf{V}^T \otimes \mathbf{V}) \mathbf{K}$$

An important property of complex M -estimators

- Let \mathbf{V}_N an estimate of Hermitian positive-definite matrix \mathbf{V} that satisfies

$$\sqrt{N} (\text{vec}(\mathbf{V}_N - \mathbf{V})) \xrightarrow{d} \mathbb{CN}(\mathbf{0}, \boldsymbol{\Sigma}, \boldsymbol{\Omega}), \quad (5)$$

with

$$\begin{cases} \boldsymbol{\Sigma} = \nu_1 \mathbf{V}^T \otimes \mathbf{V} + \nu_2 \text{vec}(\mathbf{V}) \text{vec}(\mathbf{V})^H, \\ \boldsymbol{\Omega} = \nu_1 (\mathbf{V}^T \otimes \mathbf{V}) \mathbf{K} + \nu_2 \text{vec}(\mathbf{V}) \text{vec}(\mathbf{V})^T, \end{cases}$$

where ν_1 and ν_2 are any real numbers.

e.g.

	SCM	M -estimators	Tyler
ν_1	1	σ_1	$(m+1)/m$
ν_2	0	σ_2	$-(m+1)/m^2$
...	More accurate		More robust

- Let $H(\mathbf{V})$ be a r -multivariate function on the set of Hermitian positive-definite matrices, with continuous first partial derivatives and such as $H(\mathbf{V}) = H(\alpha \mathbf{V})$ for all $\alpha > 0$, e.g. the ANMF statistic, the MUSIC statistic.

An important property of complex M -estimators

Theorem 2 (Asymptotic distribution of $H(\mathbf{V}_N)$)

$$\sqrt{N} (H(\mathbf{V}_N) - H(\mathbf{V})) \xrightarrow{d} \mathcal{CN}(\mathbf{0}_{r,1}, \boldsymbol{\Sigma}_H, \boldsymbol{\Omega}_H) \quad (6)$$

where $\boldsymbol{\Sigma}_H$ and $\boldsymbol{\Omega}_H$ are defined as

$$\begin{aligned} \boldsymbol{\Sigma}_H &= \nu_1 H'(\mathbf{V})(\mathbf{V}^T \otimes \mathbf{V})H'(\mathbf{V})^H, \\ \boldsymbol{\Omega}_H &= \nu_1 H'(\mathbf{V})(\mathbf{V}^T \otimes \mathbf{V})\mathbf{K}H'(\mathbf{V})^T, \end{aligned}$$

where $H'(\mathbf{V}) = \left(\frac{\partial H(\mathbf{V})}{\partial \text{vec}(\mathbf{V})} \right)$.

$H(SCM)$ and $H(M\text{-estimators})$ share the same asymptotic distribution (differs from σ_1)

Application: Detection using the ANMF test

- In a m -vector \mathbf{y} , detecting a complex known signal $\mathbf{s} = \alpha \mathbf{p}$ embedded in an additive noise \mathbf{z} (with covariance matrix \mathbf{V}), can be written as the following statistical test:

$$\begin{cases} \text{Hypothesis } H_0: & \mathbf{y} = \mathbf{z} & \mathbf{y}_n = \mathbf{z}_n & n = 1, \dots, N \\ \text{Hypothesis } H_1: & \mathbf{y} = \mathbf{s} + \mathbf{z} & \mathbf{y}_n = \mathbf{z}_n & n = 1, \dots, N \end{cases}$$

where the \mathbf{z}_n 's are N "signal-free" independent observations (secondary data) used to estimate the noise parameters.

- Let \mathbf{V}_N be an estimate of \mathbf{V} .

ANMF test

$$\Lambda(\mathbf{V}_N) = \frac{|\mathbf{p}^H \mathbf{V}_N^{-1} \mathbf{y}|^2}{(\mathbf{p}^H \mathbf{V}_N^{-1} \mathbf{p})(\mathbf{y}^H \mathbf{V}_N^{-1} \mathbf{y})} \underset{H_0}{\overset{H_1}{\gtrless}} \lambda$$

One has $\Lambda(\mathbf{V}_N) = \Lambda(\alpha \mathbf{V}_N)$ for any $\alpha > 0$.

Probabilities of false alarm

P_{fa} -threshold relation in the Gaussian case of $\Lambda(SCM)$ (finite N)

$$P_{fa} = (1 - \lambda)^{a-1} {}_2F_1(a, a - 1; b - 1; \lambda), \quad (7)$$

where $a = N - m + 2$, $b = N + 2$ and ${}_2F_1$ is the Hypergeometric function.

From theorem 2, one has both results

P_{fa} -threshold relation of $\Lambda(M\text{-est})$ for CES distributions

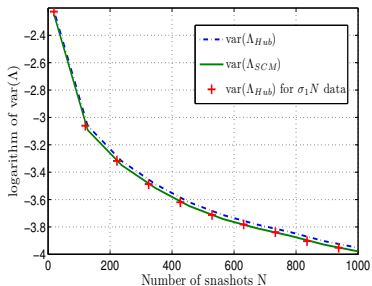
For N large and any elliptically distributed noise, the PFA is still given by (7) if we replace N by N/ν_1 .

P_{fa} -threshold relation of $\Lambda(M\text{-est})$ for CES distributions

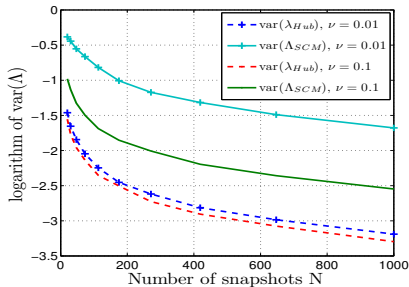
$$\sqrt{N} (\Lambda(\mathbf{V}_N) - \Lambda(\mathbf{V})) \xrightarrow{d} \mathbb{C}\mathcal{N} \left(\mathbf{0}, 2\nu_1 \Lambda(\mathbf{V}) (\Lambda(\mathbf{V}) - 1)^2 \right)$$

Simulations

- Complex Huber's M -estimator.
- Figure 1: Gaussian context, here $\sigma_1 = 1.066$.
- Figure 2: K-distributed clutter (shape parameter: 0.1, and 0.01).



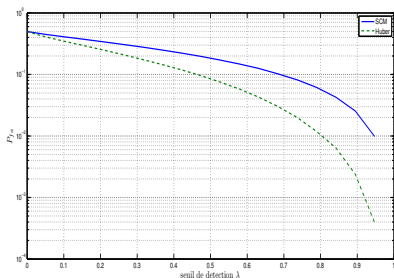
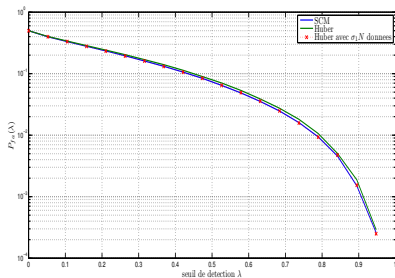
Thm validation (even for small N)



Interest of the M -estimators

Simulations: Probabilities of False Alarm

- Complex Huber's M -estimator.
- Figure 1: Gaussian context, here $\sigma_1 = 1.066$.
- Figure 2: K-distributed clutter (shape parameter: 0.1).



Validation of theorem (even for small N)

Interest of the M -estimators for False Alarm regulation

MUSIC method for DoA estimation

- K direction of arrival θ_k on m antennas
- Gaussian stationary narrowband signal with DoA 20° with additive noise.
- the DoA is estimated from N snapshots, using the SCM and the Huber's M -estimator.

$$\mathbf{z}_t = \sum_{k=1}^K \sqrt{p_k} \mathbf{s}(\theta_k) \mathbf{y}_{k,t} + \sigma \mathbf{w}_t$$

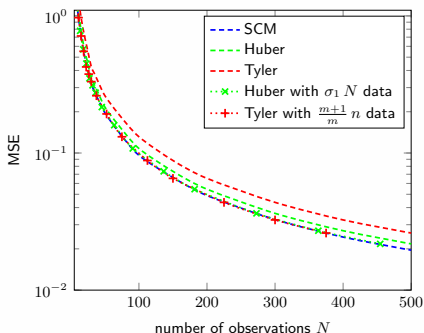
$$\begin{cases} H(\mathbf{V}) &= \gamma(\theta) = \mathbf{s}(\theta)^H \mathbf{E}_W \mathbf{E}_W^H \mathbf{s}(\theta), & (\mathbf{V} \text{ known}) \\ H(\mathbf{V}_N) &= \hat{\gamma}(\theta) = \sum_{i=1}^{m-K} \lambda_i \mathbf{s}(\theta)^H \hat{\mathbf{e}}_i \hat{\mathbf{e}}_i^H \mathbf{s}(\theta) = H(\alpha \mathbf{V}_N), & (\mathbf{V} \text{ unknown}) \end{cases}$$

where λ_i (resp. $\hat{\mathbf{e}}_i$) are the eigenvalues (resp. eigenvectors) of \mathbf{V}_N .

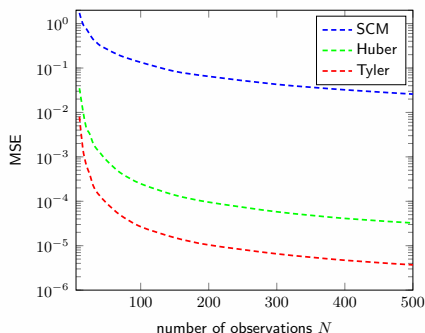
The Mean Square Error (MSE) between the estimated angle $\hat{\theta}$ and the real angle θ is then computed (case of one source).

Simulation using the MUSIC method

- A $m = 3$ ULA with half wavelength sensors spacing is used,
- Gaussian stationary narrowband signal with DoA 20° with additive noise.
- the DoA is estimated from N snapshots, using the SCM, the Huber's M -estimator and the FP estimator.



(a) White Gaussian additive noise



(b) K-distributed additive noise ($\nu = 0.1$)

Figure: MSE of $\hat{\theta}$ vs the number N of observations, with $m = 3$.

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III. Random Matrix Theory

- Interest of RMT: A very simple example
- Classical Results
- Robust RMT
- Applications to DoA estimation

IV. Regularized M -estimators and link to RMT

V. Conclusions and perspectives

Interest of RMT: A very simple example...

Problem: Estimation of 1 DoA embedded in white Gaussian noise

$$\mathbf{z}_t = \sqrt{p}\mathbf{s}(\theta)\mathbf{y}_t + \mathbf{w}_t$$

where the \mathbf{w}_t 's are n independent realizations of circular white Gaussian noise, i.e. $\mathbf{w}_t \sim \mathbb{C}\mathcal{N}(0, \mathbf{I})$.

Classical approach

$$\blacksquare \hat{\mathbf{S}}_N = \frac{1}{N} \sum_{t=1}^N \mathbf{w}_t \mathbf{w}_t^H \xrightarrow[n \rightarrow \infty]{} \mathbf{I}$$

- Then, MUSIC algorithm allows to estimate the DoA...

What happens when the dimension m is large?

$$\blacksquare \hat{\mathbf{S}}_N = \frac{1}{N} \sum_{t=1}^N \mathbf{w}_t \mathbf{w}_t^H \not\xrightarrow[m, n \rightarrow \infty]{} \mathbf{I}$$

- Then, MUSIC algorithm **IS NOT** the best way to estimate the DoA...

Classical approach: $N \gg m$

e.g. STAP context, 4 sensors and 64 pulses, $m = 256$ and $N = 10^4$

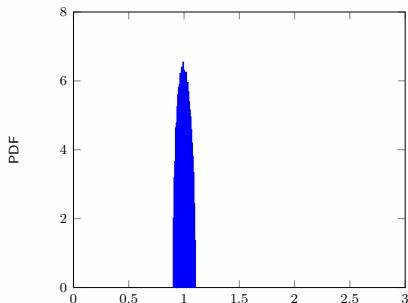


Figure: Empirical distribution for the eigenvalues of the SCM in the case of a white Gaussian noise of dimension $m = 256$ for $N = 10^4$ secondary data

What happens when the dimension m is large? (compared to N)
STAP context, 4 sensors and 64 pulses, $m = 256$ and $N = 10^3$

Marcenko-Pastur Law...

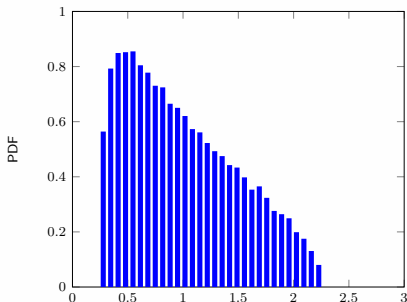


Figure: Empirical distribution for the eigenvalues of the SCM in the case of a white Gaussian noise of dimension $m = 256$ for $N = 10^3$ secondary data

What happens when the dimension m is large? (compared to N)
STAP context, 4 sensors and 64 pulses, $m = 256$ and $N = 500$

Marcenko-Pastur Law...

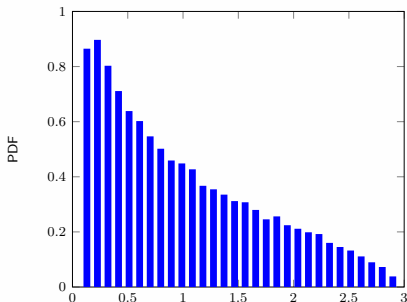
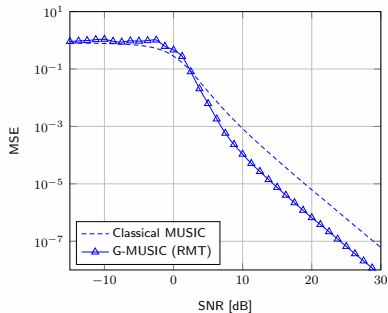


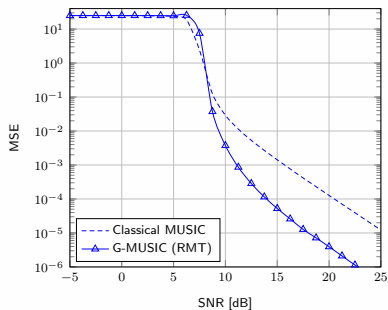
Figure: Empirical distribution for the eigenvalues of the SCM in the case of a white Gaussian noise of dimension $m = 256$ for $N = 500$ secondary data

Consequences

Bad assumptions \implies Bad performance



(a) 50 data of size 10



(b) 250 data of size 50

Figure: MSE on the different DoA estimators for $K = 1$ source embedded in an additive white Gaussian noise

RMT - Classical results

Assumptions:

- $N, m \rightarrow \infty$ and $\frac{m}{N} \rightarrow c \in (0, 1)$ and $\widehat{\mathbf{S}}_N = \frac{1}{N} \sum_{i=1}^N \mathbf{z}_i \mathbf{z}_i^H$ the SCM
- $(\mathbf{z}_1, \dots, \mathbf{z}_N)$ be a N -sample, i.i.d (i.e. $E[\mathbf{z}_i^{(j)} \mathbf{z}_k^{(l)}] = 0$) with finite fourth-order moment.

Remark: CES dist. do not respect this assumptions!

Thus one has:

$$1) F^{\widehat{\mathbf{S}}_N} \Rightarrow F^{MP}$$

where $F^{\widehat{\mathbf{S}}_N}$ (resp. F^{MP}) stands for the distribution of the eigenvalues of $\widehat{\mathbf{S}}_N$ (resp. the Marcenko-Pastur distribution) and \Rightarrow stands for the weak convergence.

The MP PDF is defined by

$$\mu(x) = \begin{cases} (1 - \frac{1}{c}) \mathbf{1}_{x=0} + f(x) & \text{if } c > 1 \\ f(x) & \text{if } c \in (0, 1] \end{cases}$$

$$\text{with } f(x) = \frac{1}{2\pi\sigma^2} \frac{\sqrt{(c_+ - x)(x - c_-)}}{cx} \mathbf{1}_{x \in [c_-, c_+]} \text{ and } c_{\pm} = \sigma^2 (1 \pm \sqrt{c})^2.$$

RMT - Classical results

Exploiting the MP dist for the SCM eigenvalues leads to a new MUSIC statistic:

$$2) \hat{\gamma}(\theta) = \sum_{i=1}^m \beta_i \mathbf{s}(\theta)^H \hat{\mathbf{e}}_i \hat{\mathbf{e}}_i^H \mathbf{s}(\theta) \text{ is the G-MUSIC statistic (Mestre, 2008)}$$

where

$$\beta_i = \begin{cases} 1 + \sum_{k=m-K+1}^m \left(\frac{\hat{\lambda}_k}{\hat{\lambda}_i - \hat{\lambda}_k} - \frac{\hat{\mu}_k}{\hat{\lambda}_i - \hat{\mu}_k} \right) & , i \leq m - K \\ - \sum_{k=1}^{m-K} \left(\frac{\hat{\lambda}_k}{\hat{\lambda}_i - \hat{\lambda}_k} - \frac{\hat{\mu}_k}{\hat{\lambda}_i - \hat{\mu}_k} \right) & , i > m - K \end{cases}$$

with $\hat{\lambda}_1 \leq \dots \leq \hat{\lambda}_m$ (resp. $\hat{\mathbf{e}}_1, \dots, \hat{\mathbf{e}}_m$ the eigenvalues (resp. the eigenvectors) of $\hat{\mathbf{S}}_N$ and $\hat{\mu}_1 \leq \dots \leq \hat{\mu}_m$ the eigenvalues of $\text{diag}(\hat{\boldsymbol{\lambda}}) - \frac{1}{m} \sqrt{\hat{\boldsymbol{\lambda}}} \sqrt{\hat{\boldsymbol{\lambda}}}^T$, $\hat{\boldsymbol{\lambda}} = (\hat{\lambda}_1, \dots, \hat{\lambda}_m)^T$.

Remark: Contrary to MUSIC or Robust-MUSIC, all the eigenvectors are used to compute G-MUSIC.

Robust RMT

Assumptions: (Couillet, 2014)

- $N, m \rightarrow \infty$ and $\frac{m}{N} \rightarrow c \in (0, 1)$ and \mathbf{V}_N a M -estimator (with previous assumptions)
- $(\mathbf{z}_1, \dots, \mathbf{z}_N)$ be a N -sample, i.i.d (!!!!!) with finite fourth-order moment

Thus, it is shown that:

1) There exists a unique solution to the M -estimator fixed-point equation for all large m a.s. The recursive algorithm associated converges to this solution.

2) $\|\phi^{-1}(1) \mathbf{V}_N - \widehat{\mathbf{S}}_N\| \xrightarrow{a.s.} 0$ when $N, m \rightarrow \infty$ and $\frac{m}{N} \rightarrow c$
where $\|\cdot\|$ stands for the spectral norm and ϕ such that $\phi(t) = t.u(t)$.

Remark: This result is similar to those presented in the classical asymptotic regime (m fixed and $N \rightarrow +\infty$).

Robust RMT

2) is the key result! Notably, it implies that

Classical results in RMT can be extended to the M -estimators

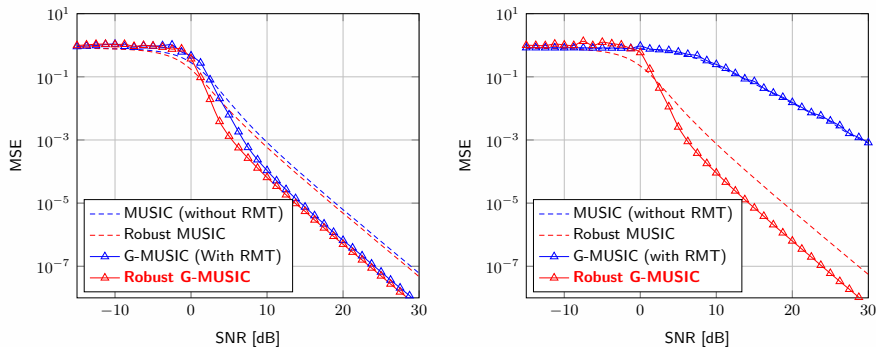
3) $\hat{\gamma}(\theta) = \sum_{i=1}^m \beta_i \mathbf{s}(\theta)^H \hat{\mathbf{e}}_i \hat{\mathbf{e}}_i^H \mathbf{s}(\theta)$ is STILL the G-MUSIC statistic for the M -estimators

where

$$\beta_i = \begin{cases} 1 + \sum_{k=m-K+1}^m \left(\frac{\hat{\lambda}_k}{\hat{\lambda}_i - \hat{\lambda}_k} - \frac{\hat{\mu}_k}{\hat{\lambda}_i - \hat{\mu}_k} \right) & , i \leq m - K \\ - \sum_{k=1}^{m-K} \left(\frac{\hat{\lambda}_k}{\hat{\lambda}_i - \hat{\lambda}_k} - \frac{\hat{\mu}_k}{\hat{\lambda}_i - \hat{\mu}_k} \right) & , i > m - K \end{cases}$$

with $\hat{\lambda}_1 \leq \dots \leq \hat{\lambda}_m$ (resp. $\hat{\mathbf{e}}_1, \dots, \hat{\mathbf{e}}_m$ the eigenvalues (resp. the eigenvectors) of \mathbf{V}_N and $\hat{\mu}_1 \leq \dots \leq \hat{\mu}_m$ the eigenvalues of $\text{diag}(\hat{\boldsymbol{\lambda}}) - \frac{1}{m} \sqrt{\hat{\boldsymbol{\lambda}}} \sqrt{\hat{\boldsymbol{\lambda}}}^T$, $\hat{\boldsymbol{\lambda}} = (\hat{\lambda}_1, \dots, \hat{\lambda}_m)^T$.

Application to DoA estimation with MUSIC for different additive clutter



(a) Homogeneous noise (\simeq Gaussian), 50 data of size 10
(b) Heterogeneous clutter, 50 data of size 10

Figure: MSE performance of the various MUSIC estimators for $K = 1$ source

Resolution probability of 2 sources

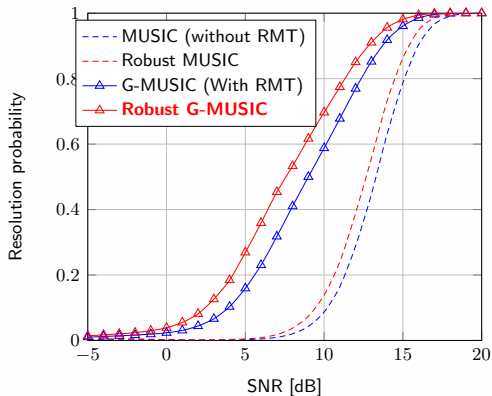


Figure: Resolution performance of the MUSIC estimators in homogeneous clutter for 50 data of size 10

Pros and Cons of these results

■ Advantages

- Original results on robust RMT
- Now, possibility of using robust estimators in a RMT context: extension of classical RMT results such DoA estimation (done), sources power estimation, number of sources estimation (challenging problem), detection...
- Great improvement: sources resolution, MUSIC statistic est.

■ Limitations

- Assumption of independence, i.e. not CES dist:

$$\mathbf{z}_i = \begin{pmatrix} \tau_1 x_i^{(1)} \\ \vdots \\ \tau_m x_i^{(m)} \end{pmatrix} \text{ instead of } \mathbf{z}_i = \tau_i \begin{pmatrix} x_i^{(1)} \\ \vdots \\ x_i^{(m)} \end{pmatrix}$$

where all the quantity are independent (means \neq random amplitude on the different sensors).

- Improvement on MSE is valid for the MUSIC statistic estimate and NOT for the DoA estimate.

Robust RMT under CES distributions

- Previous results remain valid under CES distributions, i.e. where τ_i are r.va. with unknown PDF (M -estimators, (Couillet, 2015)).

Technical condition: For each $a > b > 0$, one has

$$\lim_{t \rightarrow \infty} \frac{\limsup_N \nu_N([t, \infty))}{\phi(at) - \phi(bt)} \rightarrow 0. \text{ where } \nu_N = \frac{1}{N} \sum_{i=1}^N \delta_{\tau_i} \text{ and } \phi(t) = t.u(t).$$

Meaning: one has to control the queue of the dist. of τ_i .

- Also valid for Tyler's estimator (Zhang, 2016): $\phi(t) = m, \forall t > 0$.
More tight condition but same idea for the proof.

Robust RMT under CES distributions

Results on the eigenvalues distributions of the M -estimators for CES

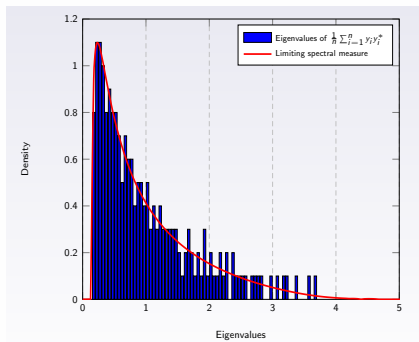
R. Couillet, F. Pascal, and J. W. Silverstein, “The Random Matrix Regime of Maronna’s M -estimator with elliptically distributed samples”, *JMVA*, vol. 139, 2015.

Ideas of the proofs? Break and discussions.

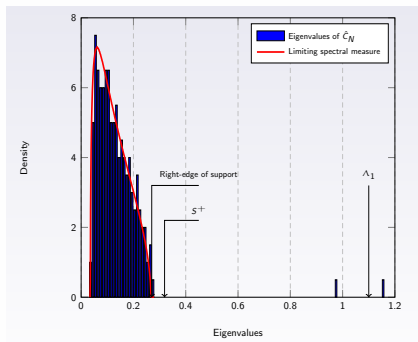
Results on the eigenvalues distributions of the Tyler’s estimator for CES

T. Zhang, X. Cheng, and A. Singer, “Marchenko-Pastur Law for Tyler’s and Maronna’s M -estimators”, arXiv preprint arXiv:1401.3424, 2016.

Robust RMT under CES distributions



(a) SCM

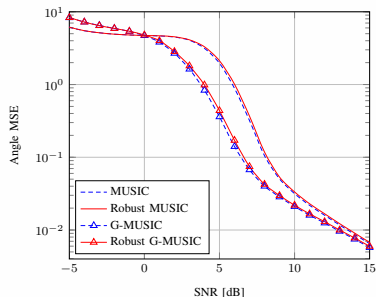


(b) Student M -estimator

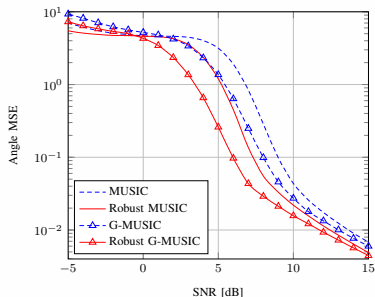
Histogram of the eigenvalues of the SCM and a M -estimator against the limiting spectral measure, with 2 sources, $p_1 = p_2 = 1$, $m = 200$, $N = 1000$, Student-t distributions

Robust RMT under CES distributions

MSE on the DoA estimation



(c) Gaussian

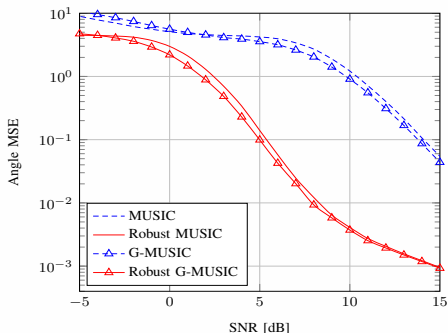


(d) K-dist ($\nu = 1$, homogeneous)

MSE vs SNR of the DoA estimation in the case of 2 sources ($\theta_1 = 14^\circ$ and $\theta_2 = 18^\circ$), for Gaussian noise and K-distributed noise, where $N = 100$ and $m = 20$.

Robust RMT under CES distributions

MSE on the DoA estimation

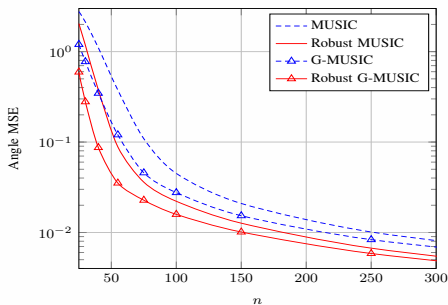


K-dist ($\nu = 0.11$, heterogeneous)

MSE vs SNR of the DoA estimation in the case of 2 sources ($\theta_1 = 14^\circ$ and $\theta_2 = 18^\circ$), for Gaussian noise and K-distributed noise, where $N = 100$ and $m = 20$.

Interest on sources resolution

Robust RMT under CES distributions



MSE vs the ration m/N of the DoA estimation in the case of 2 sources ($\theta_1 = 14^\circ$ and $\theta_2 = 18^\circ$), for homogeneous K-distributed noise, where $SNR = 10dB$ and $m = 20$.

I. Introduction

II. Estimation, background and applications

III. Random Matrix Theory

IV. Regularized M -estimators and link to RMT

- Motivations and definitions
- Optimization and detection

V. Conclusions and perspectives

Motivations

Some advantages

- Regularized problem (cf. part A), with norm penalties (e.g. for sparsity)
- Combined with M -estimators \Rightarrow robustness to outliers
- May allow to include *a priori* informations
- Case of small number of observations or under-sampling $N < m$: matrix is not invertible \Rightarrow Problem when using M -estimators or Tyler's estimator!

It is an active research on this topic:
see the works of Yuri Abramovich, Olivier Besson, Romain Couillet,
Mathew McKay, Ami Wiesel...

Regularized Tyler's estimators (RTE)

Chen estimator

$$\widehat{\Sigma}_C(\rho) = (1 - \rho) \frac{m}{N} \sum_{i=1}^N \frac{\mathbf{z}_i \mathbf{z}_i^H}{\mathbf{z}_i^H \widehat{\Sigma}_C^{-1}(\rho) \mathbf{z}_i} + \rho \mathbf{I}$$

subject to the constraint $\text{Tr}(\widehat{\Sigma}_C(\rho)) = m$ and for $\rho \in (0, 1]$.

- Originally introduced in (Abramovich, 2007)
- Existence, uniqueness and algorithm convergence proved in (Chen, 2011)
Y. Chen, A. Wiesel, and A. O. Hero, "Robust shrinkage estimation of high-dimensional covariance matrices," *Signal Processing, IEEE Transactions on*, vol. 59, no. 9, pp. 4097-4107, 2011.

Remark: Constraint $\text{Tr}(\widehat{\Sigma}_C(\rho)) = m$ has two interests:

- Allowing ρ to live in $[0, 1]$
- Making the prove easier

Regularized Tyler's estimators

Pascal estimator

$$\widehat{\Sigma}_P(\rho) = (1 - \rho) \frac{m}{N} \sum_{i=1}^N \frac{\mathbf{z}_i \mathbf{z}_i^H}{\mathbf{z}_i^H \widehat{\Sigma}_P^{-1}(\rho) \mathbf{z}_i} + \rho \mathbf{I}$$

subject to the **no** trace constraint but for $\rho \in (\bar{\rho}, 1]$, where $\bar{\rho} := \max(0, 1 - N/m)$.

- Existence, uniqueness and algorithm convergence proved in (Pascal, 2013)
F. Pascal, Y. Chitour, and Y. Quek, "Generalized robust shrinkage estimator and its application to STAP detection problem," *Signal Processing, IEEE Transactions on*, vol. 62, pp. 5640-5651, Nov. 2014.
- $\widehat{\Sigma}_P(\rho)$ (naturally) verifies $\text{Tr}(\widehat{\Sigma}_P^{-1}(\rho)) = m$ for all $\rho \in (0, 1]$

Regularized Tyler's estimators

The main challenge is to find the optimal ρ !

According to the applications... **MSE, detection performances...**

One (theoretical) answer is given thanks to RMT in ...

R. Couillet and M. R. McKay, "Large Dimensional Analysis and Optimization of Robust Shrinkage Covariance Matrix Estimators," *Journal of Multivariate Analysis*, vol. 131, pp. 99-120, 2014.

where it is also proved that

- Both estimators have asymptotically (RMT regime) the same performance (achieved for a different value of beta)
- They asymptotically perform as a normalized version of the Ledoit-Wolf estimator (similar to previous results).

O. Ledoit and M. Wolf, "A well-conditioned estimator for large-dimensional covariance matrices," *Journal of multivariate analysis*, vol. 88, no. 2, pp. 365-411, 2004.

Regularized Tyler's estimators

Objective: Robust estimate of $\mathbf{M} = E[\mathbf{z}_i \mathbf{z}_i^H]$, for $\mathbf{z}_1, \dots, \mathbf{z}_N \in \mathbb{C}^m$ i.i.d. with

- $\mathbf{z}_i = \sqrt{\tau_i} \mathbf{M}^{1/2} \mathbf{x}_i$, \mathbf{x}_i has i.i.d. entries, $E[\mathbf{x}_i] = \mathbf{0}$, $E[\mathbf{x}_i \mathbf{x}_i^H] = \mathbf{I}$
- $\tau_i > 0$ random impulses with $E[\tau_i] = 1$.
- m fixed and $N \rightarrow \infty$ (Classical asymptotics!)

OR

- $\mathbf{z}_i = \sqrt{\tau_i} \mathbf{M}^{1/2} \mathbf{x}_i$, \mathbf{x}_i has i.i.d. entries, $E[\mathbf{x}_i] = \mathbf{0}$, $E[\mathbf{x}_i \mathbf{x}_i^H] = \mathbf{I}$
- $\tau_i > 0$ random impulses with $E[\tau_i] = 1$.
- $c_m \triangleq \frac{m}{N} \rightarrow c$ as $m, N \rightarrow \infty$
- few data: $m \sim N$.

Find “optimal” regularized parameter!

RTE Asymptotics

Assumptions: m fixed and $N \rightarrow +\infty$

Let us set

$$\Sigma_0(\rho) = m(1 - \rho)E \left[\frac{\mathbf{z}\mathbf{z}^H}{\mathbf{z}^H \Sigma_0^{-1}(\rho)\mathbf{z}} \right] + \rho \mathbf{I}$$

for $\rho \in (\bar{\rho}, 1]$, where $\bar{\rho} := \max(0, 1 - N/m)$.

Then, for any $\kappa > 0$, one has

$$\sup_{\rho \in [\kappa, 1]} \left\| \hat{\Sigma}_P(\rho) - \Sigma_0(\rho) \right\| \xrightarrow[m \text{ fixed, } N \rightarrow \infty]{a.s.} 0$$

Remark: Of course, $\Sigma_0(\rho) \neq \mathbf{M}!!!$ What is $\Sigma_0(\rho)$? ... it can be shown that they share the same eigenvectors space.

RTE Asymptotics

Characterization of $\Sigma_0(\rho)$

Let us first denote $\Sigma_0 = \Sigma_0(\rho)$.

- Multiplying by $\mathbf{M}^{-1/2}$, one obtains:

$$\mathbf{M}^{-1/2} \Sigma_0 \mathbf{M}^{-1/2} = m(1 - \rho) E \left[\frac{\mathbf{x}\mathbf{x}^H}{\mathbf{x}^H \mathbf{M}^{1/2} \Sigma_0^{-1} \mathbf{M}^{1/2} \mathbf{x}} \right] + \rho \mathbf{M}^{-1}$$

- Let the eigenvalue decomposition of $\mathbf{M}^{-1/2} \Sigma_0 \mathbf{M}^{-1/2} = \mathbf{V}\mathbf{D}\mathbf{V}^H$.

- Then, $m(1 - \rho) E \left[\frac{\mathbf{x}\mathbf{x}^H}{\mathbf{x}^H \mathbf{D} \mathbf{x}} \right] + \rho \mathbf{V}^H \mathbf{M}^{-1} \mathbf{V} = \mathbf{D}^{-1}$

$\implies E \left[\frac{\mathbf{x}\mathbf{x}^H}{\mathbf{x}^H \mathbf{D} \mathbf{x}} \right] = \text{diag}(\alpha_1, \dots, \alpha_m)$ is diagonal implying Σ_0 and \mathbf{M} share the same eigenvector space.

Lemma If $\mathbf{D} = \text{diag}(d_1, \dots, d_m)$, then α_i are given by

$$\alpha_i = \frac{1}{2^m} \frac{1}{m} \frac{1}{\prod_{j=1}^m d_j} F_D^{(m)} \left(m, 1, \dots, 2, 1, \dots, 1, m+1, \frac{d_1 - 1/2}{d_1}, \dots, \frac{d_m - 1/2}{d_m} \right)$$

where $F_D^{(m)}$ is the Lauricella's type D hypergeometric function.

RTE Asymptotics

Characterization of $\Sigma_0(\rho)$

- Denote by $\alpha_i(\{d_j\}_{j=1}^m) = E \left[\frac{|x_i|^2}{\mathbf{x}^H \mathbf{D} \mathbf{x}} \right]$. Then

$$m(m-1)\alpha_i(\{d_i\}_{i=1}^m) + \frac{\rho}{\lambda_i} = \frac{1}{d_i},$$

where λ_i are the eigenvalues of $\widehat{\Sigma}_P(\rho)$: $\widehat{\Sigma}_P(\rho) = \mathbf{V} \mathbf{\Delta} \mathbf{V}^H$ with $\mathbf{\Delta} = \text{diag}(\lambda_1, \dots, \lambda_m)$ and $\lambda_1 \geq \lambda_2 \dots \geq \lambda_m$.

- Start from $d_1^{(0)}, \dots, d_m^{(0)}$ and compute iteratively

$$d_i^{(t+1)} = \frac{1}{\frac{\rho}{\lambda_i} + m(1-m)\alpha_i(\text{diag}(\mathbf{d}^{(t)}))}$$

until convergence. If $d_{1,\infty}, \dots, d_{m,\infty}$ are the obtained values, then...

- Set $s_{i,\infty} = \lambda_i d_{i,\infty}$, Then,

$$\Sigma_0 = \mathbf{V} \text{diag}(s_{1,\infty}, \dots, s_{m,\infty}) \mathbf{V}^H.$$

RTE Asymptotics

Assumptions: m fixed and $N \rightarrow +\infty$

Similarly to M -estimators, one can establish a CLT:

Theorem 1 (Asymptotic distribution of $\widehat{\Sigma}_P(\rho)$)

$$\sqrt{N} \operatorname{vec}(\widehat{\Sigma}_P(\rho) - \Sigma_0(\rho)) \xrightarrow{d} \mathbb{CN}(\mathbf{0}, \mathbf{M}_1, \mathbf{M}_2), \quad (8)$$

where \mathbb{CN} is the complex Gaussian distribution, \mathbf{M}_1 the CM and \mathbf{M}_2 the pseudo CM.

RMT Asymptotic Behavior

Theorem (Asymptotic Behavior (Couillet-McKay, 2014))

For $\varepsilon \in (0, \min\{1, c^{-1}\})$, define $\hat{\mathcal{R}}_\varepsilon = [\varepsilon + \max\{0, 1 - c^{-1}\}, 1]$.

Then, as $m, N \rightarrow \infty$, $m/N \rightarrow c \in (0, \infty)$,

$$\sup_{\rho \in \hat{\mathcal{R}}_\varepsilon} \left\| \hat{\Sigma}_P(\rho) - \tilde{\mathbf{S}}_m(\rho) \right\| \xrightarrow{\text{a.s.}} 0$$

with

$$\tilde{\mathbf{S}}_m(\rho) = \frac{1}{\underline{\gamma}(\rho)} \frac{1 - \rho}{1 - (1 - \rho)c} \frac{1}{N} \sum_{i=1}^N \mathbf{M}^{\frac{1}{2}} \mathbf{x}_i \mathbf{x}_i^H \mathbf{M}^{\frac{1}{2}} + \rho \mathbf{I}$$

and $\underline{\gamma}(\rho)$ unique positive solution to equation

$$1 = \frac{1}{m} \text{Tr} \left(\mathbf{M} (\rho \underline{\gamma}(\rho) \mathbf{I} + (1 - \rho) \mathbf{M})^{-1} \right).$$

Moreover, $\rho \mapsto \underline{\gamma}(\rho)$ continuous on $(0, 1]$.

Asymptotic Model Equivalence

Theorem (Model Equivalence (Couillet-McKay, 2014))

For each $\rho \in (0, 1]$, there exist unique $\underline{\rho} \in (\max\{0, 1 - c^{-1}\}, 1]$ such that

$$\frac{\tilde{\mathbf{S}}_m(\underline{\rho})}{\frac{1}{\gamma(\underline{\rho})} \frac{1-\underline{\rho}}{1-(1-\underline{\rho})c} + \underline{\rho}} = (1 - \rho) \frac{1}{N} \sum_{i=1}^N \mathbf{M}^{\frac{1}{2}} \mathbf{x}_i \mathbf{x}_i^* \mathbf{M}^{\frac{1}{2}} + \rho \mathbf{I}.$$

Besides, $(0, 1] \rightarrow (\max\{0, 1 - c^{-1}\}, 1]$, $\rho \mapsto \underline{\rho}$ is increasing and onto.

- Estimator behaves similar to **impulsion-free Ledoit-Wolf estimator**
- **About uniformity:** Uniformity over ρ essential to find optimal values of ρ .
- $\tilde{\mathbf{S}}_m$ is unobservable!

Context

Hypothesis testing: Two sets of data

- Initial pure-noise data: $\mathbf{z}_1, \dots, \mathbf{z}_N$, $\mathbf{z}_n = \sqrt{\tau_n} \mathbf{M}^{1/2} \mathbf{x}_n$ as before.

■

$$\begin{cases} \text{Hypothesis } H_0: & \mathbf{y} = \mathbf{z} & \mathbf{y}_n = \mathbf{z}_n & n = 1, \dots, N \\ \text{Hypothesis } H_1: & \mathbf{y} = \mathbf{s} + \mathbf{z} & \mathbf{y}_n = \mathbf{z}_n & n = 1, \dots, N \end{cases}$$

with $\mathbf{z} = \sqrt{\tau} \mathbf{M}^{1/2} \mathbf{x}$, $\mathbf{s} = \alpha \mathbf{p}$, $\mathbf{p} \in \mathbb{C}^m$ **deterministic known**, α unknown.

GLRT detection test:

$$T_m(\rho) \underset{\mathcal{H}_0}{\overset{\mathcal{H}_1}{\lesssim}} \Gamma$$

for some detection threshold Γ where

$$T_m(\rho) \triangleq \frac{|\mathbf{y}^H \hat{\Sigma}_P^{-1}(\rho) \mathbf{p}|}{\sqrt{\mathbf{y}^H \hat{\Sigma}_P^{-1}(\rho) \mathbf{y}} \sqrt{\mathbf{p}^H \hat{\Sigma}_P^{-1}(\rho) \mathbf{p}}}.$$

Context

Originally found to be $\widehat{\Sigma}_P(0)$ but

- only valid for $m < N$
- $\rho \geq 0$ can only bring improvements.

Basic comments:

- For $\Gamma > 0$, as $m, N \rightarrow \infty$, $m/N \rightarrow c > 0$, under H_0 ,

$$T_m(\rho) \xrightarrow{\text{a.s.}} 0.$$

⇒ Zero false alarm, trivial result.

- Non-trivial solutions for $\Gamma = \gamma/\sqrt{m}$, $\gamma > 0$ fixed.

Objectives

Objective: For finite but large m, N , solve

$$\rho^* = \operatorname{argmin}_{\rho} \{P(\sqrt{m}T_m(\rho) > \gamma)\}.$$

Several steps:

- for each ρ , **central limit theorem** to evaluate

$$\lim_{\substack{m, N \rightarrow \infty \\ m/N \rightarrow c}} P(\sqrt{m}T_m(\rho) > \gamma)$$

(very involved due to intricate structure of $\widehat{\Sigma}_P$)

- find minimizing ρ
- estimate minimizing ρ

Main results

Theorem (Asymptotic detector performance (Couillet-Pascal, 2015))

As $m, N \rightarrow \infty$ with $m/N \rightarrow c \in (0, \infty)$,

$$\sup_{\rho \in \mathcal{R}_\kappa} \left| P \left(T_m(\rho) > \frac{\gamma}{\sqrt{m}} \right) - \exp \left(-\frac{\gamma^2}{2\sigma_m^2(\underline{\rho})} \right) \right| \rightarrow 0$$

with $\rho \mapsto \underline{\rho}$ aforementioned mapping and

$$\sigma_m^2(\underline{\rho}) \triangleq \frac{1}{2} \frac{\mathbf{p}^H \mathbf{M} Q_m^2(\underline{\rho}) \mathbf{p}}{\mathbf{p}^H Q_m(\underline{\rho}) \mathbf{p} \cdot \frac{1}{m} \text{Tr}(\mathbf{M} Q_m(\underline{\rho})) \cdot (1 - c(1 - \underline{\rho})^2 f(-\underline{\rho}))^2 \frac{1}{N} \text{Tr}(\mathbf{M}^2 Q_m(\underline{\rho}))}$$

with $Q_m(\underline{\rho}) \triangleq (\mathbf{I} + (1 - \underline{\rho})f(-\underline{\rho})\mathbf{M})^{-1}$.

- Limiting Rayleigh distribution (weak convergence to Rayleigh $R_m(\underline{\rho})$)
- **Remark:** σ_m and $\underline{\rho}$ not function of γ

⇒ There exists uniformly optimal ρ .

Simulation

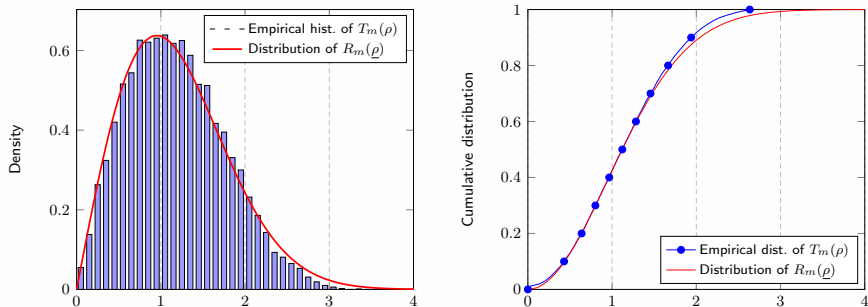


Figure: Histogram distribution function of the $\sqrt{m}T_m(\rho)$ versus $R_m(\rho)$, $m = 20$, $N = 40$ $\mathbf{p} = m^{-\frac{1}{2}}[1, \dots, 1]^T$, \mathbf{M} Toeplitz from AR of order 0.7, $\rho = 0.2$.

Simulation

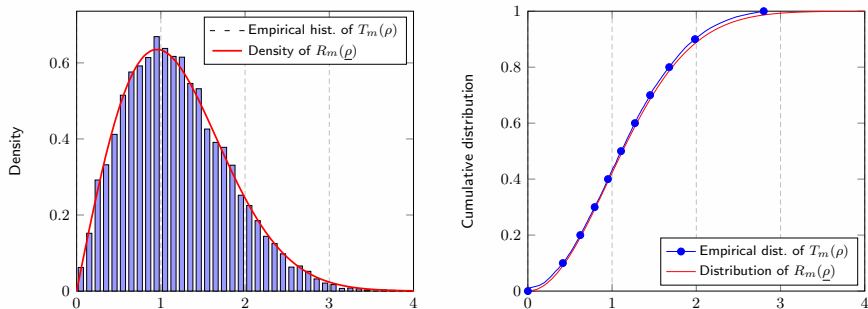


Figure: Histogram distribution function of the $\sqrt{N}T_m(\rho)$ versus $R_m(\rho)$, $m = 100$, $N = 200$ $\mathbf{p} = m^{-\frac{1}{2}}[1, \dots, 1]^T$, \mathbf{M} Toeplitz from AR of order 0.7, $\rho = 0.2$.

Empirical estimation of optimal ρ

Optimal ρ depends on unknown \mathbf{M} . We need:

- empirical estimate $\sigma_m(\underline{\rho})$
- minimize the estimate
- prove asymptotic optimality of estimate.

Theorem (Empirical performance estimation (Couillet-Pascal, 2015))

For $\rho \in (\max\{0, 1 - c_m^{-1}\}, 1)$, let

$$\hat{\sigma}_m^2(\underline{\rho}) \triangleq \frac{1}{2} \frac{1 - \rho \cdot \frac{\mathbf{p}^H \hat{\Sigma}_P^{-2}(\rho) \mathbf{p}}{\mathbf{p}^H \hat{\Sigma}_P^{-1}(\rho) \mathbf{p}}}{(1 - c_m + c_m \rho)(1 - \rho)}.$$

Also let $\hat{\sigma}_m^2(1) \triangleq \lim_{\underline{\rho} \uparrow 1} \hat{\sigma}_m^2(\underline{\rho})$.

Then

$$\sup_{\rho \in \mathcal{R}_\kappa} |\sigma_m^2(\underline{\rho}) - \hat{\sigma}_m^2(\underline{\rho})| \xrightarrow{\text{a.s.}} 0.$$

Final result

Theorem (Optimality of empirical estimator (Couillet-Pascal, 2015))

Define

$$\underline{\rho}_m^* = \operatorname{argmin}_{\{\rho \in \mathcal{R}'_\kappa\}} \{ \hat{\sigma}_m^2(\underline{\rho}) \}.$$

Then, for every $\gamma > 0$,

$$P\left(\sqrt{m}T_m(\underline{\rho}_m^*) > \gamma\right) - \inf_{\rho \in \mathcal{R}_\kappa} \{P(\sqrt{m}T_m(\rho) > \gamma)\} \rightarrow 0.$$

Simulations

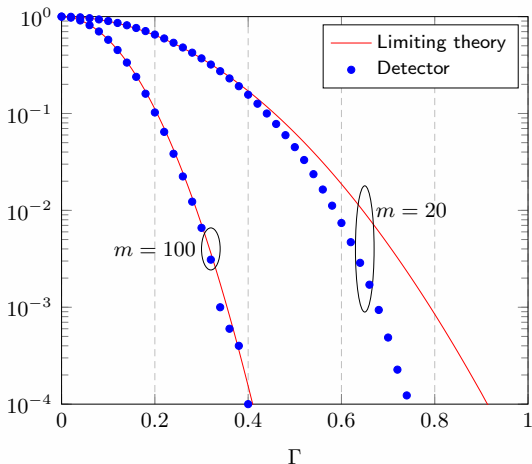


Figure: False alarm rate $P(T_m(\rho) > \Gamma)$ for $m = 20$ and $m = 100$, $\mathbf{p} = m^{-\frac{1}{2}}[1, \dots, 1]^T$, $M_{ij} = 0.7^{|i-j|}$, $c_m = 1/2$.

Analogous results can be obtained under H_1 (more useful!).

A. Kammoun, R. Couillet, F. Pascal, and M.-S. Alouini, "Optimal Design of the Adaptive Normalized Matched Filter Detector," *Information Theory, IEEE Transactions on* (submitted to), 2016. arXiv:1501.06027

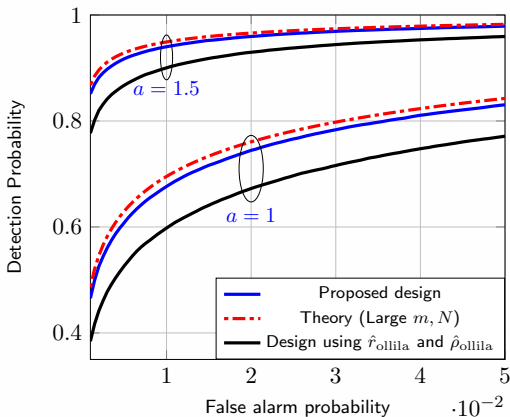


Figure: ROC curves for non-Gaussian clutters when $m = 250$ (STAP application $N_a = 10, N_p = 25$), $N = 250, f_d = 0.6$

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Conclusions and Perspectives

■ Conclusions

- Derivation of the complex M -estimators asymptotic distribution, the robust ANMF and the MUSIC statistic asymptotic distributions.
- In the Gaussian case, M -estimators built with $\sigma_1 N$ data behaves as SCM built with N data (i.e. slight loss of performance in Gaussian case).
- Better estimation in non-Gaussian cases.
- Extension to the Robust RMT and derivation of the Robust G-MUSIC method.
- Shrinkage M -estimators: one more degree of freedom (for Big data problems, robust methods...)

Conclusions and Perspectives

- Perspectives
 - Low Rank techniques for robust estimation
 - Robust estimation with a location parameter (non-zero-mean observation): e.g. Hyperspectral imaging
 - Second-order moment in RMT
 - Asymptotics for regularized robust estimators
 - RMT analysis for regularized robust estimators

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Thank you for your attention!

Questions?